

### Session 3.6 : Demonstrations

- JERICO Evaluation Testbed - A Live Demonstration of TRASYS Technology for Space Robotics 3.6-1  
*Galar dini, D.; Didot, F.\*\*; Kapellos, K.\*; Maesen, E.\*; Matthyssen, A.\*; Zastavni, N.\*; \*TRASYS, Belgium; \*\*ESA/ESTEC, The Netherlands*
- A Wheeled Mobile Device for Deployment of Surface and Subsurface Instruments and for Subsurface Sampling on Planets 3.6-2  
*Richter, L.\*; Bernasconi, M.C.\*\*; Haapanala, S.\*\*\*; Steiner, R.\*; Coste, P.\*\*\*\* \*DLR, Germany; \*\*Contraves Space, Switzerland; \*\*\*Finnish Meteorological Institute, Finland; \*\*\*\*ESA/ESTEC, The Netherlands*
- Autonomous Operations of a Micro-Rover for Geo-Science on Mars 3.6-3  
*Vergauwen, M.; Pollefeys, M.; Van Gool, L. ESAT-PSI, K.U. Leuven, Belgium*
- Shrimp: A Rover Architecture for Long-Range Martian Mission 3.6-4  
*Estier, T.\*; Piguet, R.\*; Eichhorn, R.\*\*; Siegwart, R.\* \*EPFL, Switzerland; \*\*Helbling Technik, Switzerland*
- An Investigation into Aerobot Technologies for Planetary Exploration 3.6-5  
*Barnes, D.; Summers, P.; Shaw, A.; University of Wales, United Kingdom*