

Session 3.5b: Advanced Control of Robot Systems

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| Multirobot Lightweight Object Manipulation and Assembly within Space Applications <i>Casalino, G.; Angeletti, D.; Caffaz, A.; Redini, K.; University of Genova, Italy</i> | 3.5b-1 |
| Behaviour-Based Cooperation with Application to Space Robots <i>Sequeira, J.*; Lima, P.*; Ribeiro, I.**; Sentieiro, J.*; *Instituto Superior Tecnico, Portugal; **Instituto de Sistemas e Robotica, Portugal</i> | 3.5b-2 |
| Planning Autonomously in Mobile Swarms (PAMS) <i>Grant, T.J.; Broeils, A.; Cornelissen, F.; Origin Nederland BV, The Netherlands</i> | 3.5b-3 |
| Teleoperation with Time Delays: A Survey and its Use in Space Robotics <i>Peñin, L.F.; GMV, Spain</i> | 3.5b-4 |