

Session 3.3: Exhibits Session

- Low Cost Small Experimental Facilities for Space Station and the Potential for Telepresence via Internet 3.3-1
*Nixon, D.**; Larter, N.*; **Altus Associates, The United States;*
**Technology Troubleshooter, Ireland*
- Nanokhod Micro-Rover Environmental Compatibility Requirements and Design 3.3-2
Bertrand, R.; van Winnendael, M.**; *von Hoerner & Sulger GmbH, Germany,*
***ESA/ESTEC, The Netherlands*
- Please refer to paper 3.1-4 3.3-3
- Time-Delayed Teleoperations of Space Robots 3.3-4
Penin, L.; Matusmoto, K.**; Wakabayashi, S.**; Barrientos, A.***; Mora, A.***;*
*Hernando, M.***; *GMV, Spain; **National Aerospace Laboratory of Japan, Japan;*
****Polytechnic University of Madrid, Spain*
- Some Peculiarities of Control by Free-Flying Space Robotic Module with Manipulators 3.3-5
Rutkovsky, V.; Zemlyakov, S.D.; Sukhanov, V.M.; Glumov, V.M.;
Inst. of Control Sciences of RAS, Russian Federation
- Architecture for Autonomy: from Robots to Satellites 3.3-6
Fleury, S.; Ingrand, F.; LAAS/CNRS, France
- Visual Control of Teleoperated Cellular Robots 3.3-7
Santos-Victor, J.; Sentieiro, J.; Instituto de Sistemas e Robotica, Portugal
- Improving Reusability of Behaviour based Robot Cognitive Architectures obtained through Evolution 3.3-8
Duro, R.; Becerra, J.A.; Santos, J.; Universidade da Coruna, Spain
- Experimental Activity on Grasping Objects in Free-Floating Conditions 3.3-9
Biagiotti, L.; Melchiorri, C.; Vassura, G.; University of Bologna, Italy
- Please refer to paper 3.8-1 3.3-10
- Hong Kong Micro End Effectors and Rind Grinders 3.3-11
Ng, T.C.; Yung, K.L.**; Yu, C.H.**; Chan, C.C.***;*
**Dentist, Hong Kong; **Polytechnic University, Hong Kong;*
****Solidworks Corporation, Hong Kong*
- Simulation Environments for Space Robot Design and Verification 3.3-12
Piedboeuf, J.-C.; Doyon, M.*; Archeveque, R.*; Martin, E.*; Belanger, J.**;*
**Canadian Space Agency, Canada; **Opal-RT, Canada*