

Session 3.2: Robot Mobility Concepts

- The Study of Locomotion of Small Wheeled Rovers: The MIDD Activity 3.2-1
Richter, L.; Bernasconi, M.C.**; Coste, P.***, *DLR, Germany;
Contraves Space, Switzerland; *ESA/ESTEC, The Netherlands*
- Shrimp: A Rover Architecture for Long-Range Martian Mission 3.2-2
Estier, T.; Piguët, R.*; Eichhorn, R.**; Siegwart, R.*;
*EPFL, Switzerland; **Helbing Technik, Switzerland*
- Windball: an Innovative Locomotion Concept for Long-Range
Missions and Study of Martian Wind 3.2-3
Estier, T.; Siegwart, R.; EPFL, Switzerland