

Session 3.4: Ground Control of Robot Systems on the ISS

- JERICO Evaluation Testbed - The ESA Distributed Robot Monitoring & Control Environment for Space Robotic Applications 3.4-1
Galardini, D.; Didot, F.**; Kapellos, K.*; Maesen, E.*; Matthyssen, A.*; Zastavni, N.*, *TRASYS, Belgium; **ESA/ESTEC, The Netherlands*
- The EUROPA Ground Segment 3.4-2
Leone, R.; Losito, S.*; Mugnuolo, R.*; Pasquali, F.*; Didot, F.**; Favaretto, M.***; Finotello, R.***; Terribile, A.***; Galardini, D.****; *ASI, Italy; **ESA/ESTEC, The Netherlands; ***Tecnomare SpA, Italy; ****Trasys Space, Belgium*
- A Test-Bed for the Demonstration of MSS Ground Control 3.4-3
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